a means for generating a single filtered output signal;

wherein each building block includes a means for receiving a local main input signal, a means for receiving a local auxiliary input signal, and a processing means for calculating a complex adaptive weight, and generating a local output signal, utilizing the complex adaptive weight.

Please add the following new claims:

- 17. An adaptive signal processing system as in claim 16, wherein the complex adaptive weight w_{med} comprises: a sample median value of the real part of a ratio of a main input weight training data signal to an auxiliary input weight training data signal, and a sample median value of the imaginary part of the ratio of a main input weight training data signal to an auxiliary input weight training data signal.
- 18. An adaptive signal processing system as in claim 16, wherein the complex adaptive weight w_{med} comprises a sample median value of the real part of a ratio of a main input weight training data signal to an auxiliary input weight training data signal.
- 19. An adaptive signal processing system as claimed in claim 16, wherein each building block generates the complex adaptive weight, w_{med}, by solving the equation:

$$w_{med} = \underset{k=1 \text{ to } K}{MED} \left[rea \left(\frac{z(k)^*}{x(k)^*} \right) \right] + j \left\{ \underset{k=1 \text{ to } K}{MED} \left[imag \left(\frac{z(k)^*}{x(k)^*} \right) \right] \right\}$$

where K is the number of weight training data samples, z is the local main input signal, j is the unit imaginary vector, and x is the local auxiliary input signal; and

generates the local output signal, r, by solving the equation:

$$r = z - w^*_{med} x$$
.

20. An adaptive signal processing system for receiving a plurality input signals corresponding to a common target signal and for sequentially decorrelating the input signals to cancel the correlated noise components therefrom, the adaptive signal processing system comprising:

a plurality of building blocks arranged in a cascaded configuration having N input channels and N-1 rows of building blocks, for sequentially decorrelating each of the input signals from each other of the input signals to thereby yield a single filtered output signal;

wherein each row of building blocks has a first end building block which is fed originally by a main input channel and a last end building block opposite said first end building block,

wherein each building block includes:

signal, and

a local main input channel which receives a local main input signal, a local auxiliary input channel which receives a local auxiliary input

a processing mechanism that calculates a complex adaptive weight and generates a local output signal, utilizing the complex adaptive weight;

wherein said last end building block supplies the local output signal to a separate local output channel for follow on processing.

- 21. An adaptive signal processing system as in claim 20, wherein the Nth input channel is supplied for follow on processing.
- 22. An adaptive signal processing system as in claim 20, wherein said complex adaptive weight comprises: a sample median value of the real part of a ratio of a main input weight training data signal to an auxiliary input weight training data signal, and a sample median value of the imaginary part of the ratio of a main input weight training data signal to an auxiliary input weight training data signal.
- 23. An adaptive signal processing system as in claim 20, wherein said complex adaptive weight comprises a sample median value of the real part of a ratio of a main input weight training

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data signal to an auxiliary input weight training data signal.

24. An adaptive signal processing system as in claim 20, wherein said complex adaptive weight w_{med} is generated by solving the equation:

$$w_{med} = \underset{k=1 \text{ to } K}{MED} \left[rea \left(\frac{z(k)^*}{x(k)^*} \right) \right] + j \left\{ \underset{k=1 \text{ to } K}{MED} \left[imag \left(\frac{z(k)^*}{x(k)^*} \right) \right] \right\},$$

where K is the number of weight training data samples, z is the local main input signal, j is the unit imaginary vector, and x is the local auxiliary input signal; and the local output signal r is generated by solving the equation:

$$r = z - w^*_{med} x$$
.

<u>REMARKS</u>

Claims 1-24 remain in this application. Claim 16 has been amended. Claims 17-24 have been added. Support for the amendment to claim 16 is in the specification at p. 13, lines 1-8 and in Figure 6. Support for the added claims is as follows: claims 17 and 22- in the specification at p. 8, lines 3-6 and at p. 12, line 19-p. 13, line 1; claims 18 and 23: in the specification at p. 8, lines 3-6, at p. 12, line 19-p. 13, line 1, and at p. 14, lines 16-17; claims 19 and 24: in the specification at p. 12, line 16-p. 14, line 15; claim 20: in the specification at pp. 8-24 and in the Figures; claim 21: in the specification at p. 23, line 9-p. 24, line 11.

Attached hereto is a marked-up version showing the changes made to claim 16 and reiterating the new claims. The attached page is captioned "Version with markings to show changes made and new claims added."